# Ranking Median Regression: Learning to Order through Local Consensus

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Stephan Clémençon, Anna Korba, Eric Sibony

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Télécom ParisTech

# Introduction

- Let  $\{1, \ldots, n\}$  a set of items to be ranked.
- A full ranking i<sub>1</sub> ≻ · · · ≻ i<sub>n</sub> is seen as a permutation σ ∈ 𝔅<sub>n</sub> that maps an item i<sub>j</sub> to its rank j.

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Suppose we observe  $((X_1, \Sigma_1), \dots, (X_N, \Sigma_N)$  i.i.d. copies of the pair  $(X, \Sigma)$ , where

- $X \sim \mu$ , where  $\mu$  is a distribution on some feature space  $\mathcal{X}$
- $\Sigma \sim P_X$ , conditional prob. distr. on the symmetric group  $\mathfrak{S}_n$

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#### **Goal of Ranking Regression**

Learn a predictive ranking rule  $s : \mathcal{X} \to \mathfrak{S}_n$  which given a random vector X (e.g characteristics of an user), predicts the order/permutation  $\Sigma$  on the *n* items (e.g its true preferences).

#### **Ranking Median Regression**

Formally, find  $s \in S$  minimizing the following (theoretical) **risk**:

$$\mathcal{R}(s) = \mathbb{E}_{X \sim \mu, \Sigma \sim P_X} \left[ d_\tau \left( s(X), \Sigma \right) \right], \tag{1}$$

where *d* is the Kendall's tau distance, i.e for all  $(\sigma, \sigma') \in \mathfrak{S}_n^2$ :

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#### Definition

For any  $\sigma \in \mathfrak{S}_n$ , the risk of  $\sigma$  is  $L(\sigma) = \mathbb{E}_{\Sigma \sim P}[d(\Sigma, \sigma)]$ . A Kemeny median is any

$$\sigma_P^* = \underset{\sigma \in \mathfrak{S}_n}{\operatorname{argmin}} L(\sigma) \tag{2}$$

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Optimal predictors  $s^*$  minimizing (1) are the rules that maps any point X to any Kemeny median of  $P_X$  (minimizing (2)):

$$s^* = \operatorname*{argmin}_{s \in \mathcal{S}} \mathcal{R}(s) \quad \Leftrightarrow \quad s(X) = \sigma^*_{P_X}$$

# Local Consensus Methods for Ranking Median Regressions

**Idea:** approximate  $s^*$  with piecewise constant ranking rules ( $s \in S_P$ ), by computing **local Kemeny medians**.

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$$\widehat{\mathcal{R}}_N(s) = rac{1}{N} \sum_{k=1}^N d_{\tau}(s(X_k), \ \Sigma_k)$$

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#### **Our Approach**

Generate partitions tailored to the training data and yielding a ranking rule with nearly minimum predictive error. Two methods are investigated: K-Nearest Neighbor and Decision-tree.

# Thank you!